

# Minimum-Cost Network Design with (Dis)economies of Scale

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# **Overview**

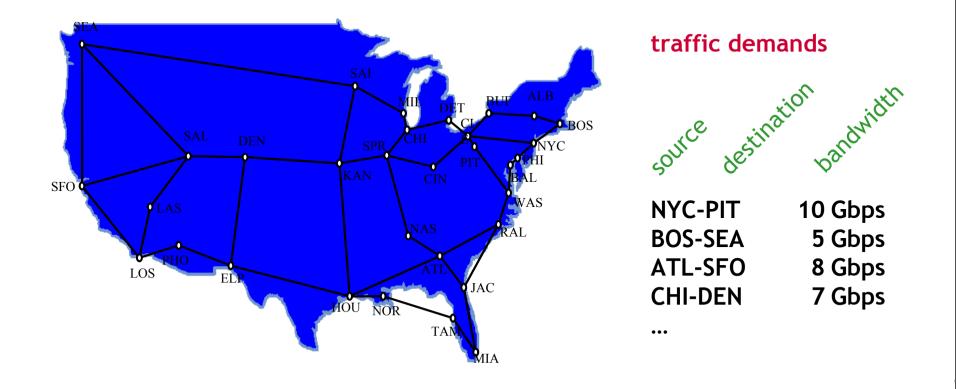
- 1. Background
  - Motivation
  - Relation to buy-at-bulk network design
- 2. Achieving a polylogarithmic approximation
  - Cost discretization
  - Well-cut-linked flow decomposition
  - Construction of expander virtual topology
  - Edge-disjoint routing
- 3. Concluding remarks



#### Network design

**Network:** carries people and/or commodities (oil, data, etc.) between a number of locations.

Example: optical-core communications network covering the United States.



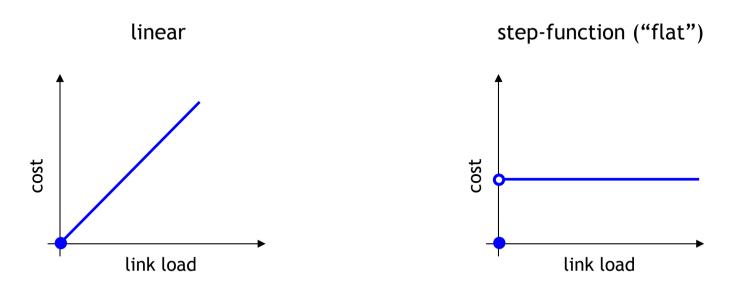
#### Network design (contd.)

Typical formulation of minimum-cost network design problem:

- Available network topology
  - Tree, ring, general graph, ...
- Set of end-to-end traffic demands
  - Single sink, all pairs, multi-commodity, ...
- A function representing the cost of a network element in relation to the traffic carried by that element
  - Uniform vs. non-uniform
- Problem-specific requirements, if any
  - Latency, fault tolerance, "hard" capacity constraints, ...
- Goal: determine a minimum-cost network that can serve all traffic demands (and respect any additional requirements)



#### Some simple cost functions

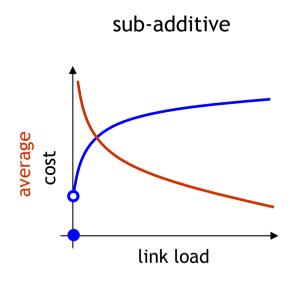


- Linear cost function ⇒ decomposes to a shortest-paths problem for each traffic demand
  - Easy solvable in polynomial time [Dijkstra]
- Step-function ("flat cost") ⇒ Steiner forest problem
  - Somewhat easy we can find a solution with at most twice the optimal cost in polynomial time (i.e. approximation ratio 2) [Agrawal-Klein-Ravi, Goemans-Williamson]





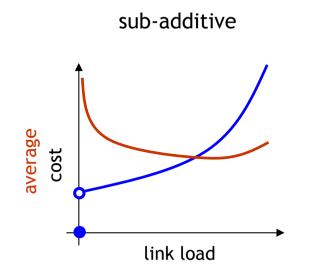
# **Buy-at-bulk cost functions**



- Sub-additive cost function (continuous or discontinuous) ⇒ buy-at-bulk network design problem
  - Sub-additivity:  $f(x_1 + x_2) \le f(x_1) + f(x_2)$
  - Models economies of scale
  - Manageable we can find a solution with at most O(log n) times or polylog(n) times the optimal cost in polynomial time (uniform/non-uniform version resp.) [Awerbuch-Azar, Chekuri-Hajiaghayi-Kortsarz-Salavatipour]



#### Energy costs and (dis)economies of scale

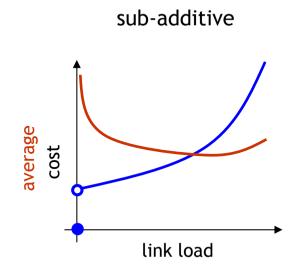


What if the cost function has the form  $f(x) = \sigma + x^{\alpha}$  for x > 0, f(0) = 0?

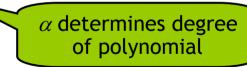
- Motivation: describes power consumption of CMOS circuits with speed scaling
- Reflects a combination of economies and diseconomies of scale
  - Similarly-shaped cost curves commonly encountered in many industries ⇒ potential for wide model applicability



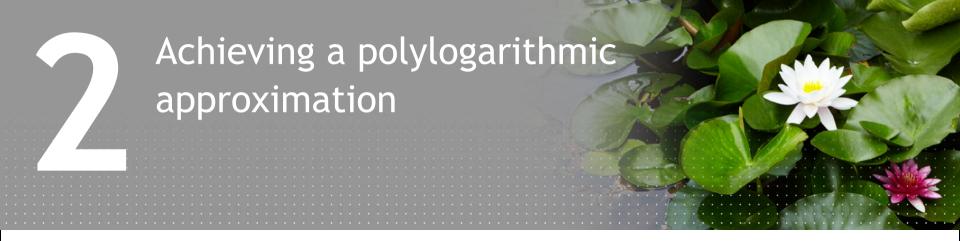
# Energy costs and (dis)economies of scale (contd.)



- Bad news: a lower bound on the approximation ratio is exponentially dependent on α [A, Andrews-Fernandez-Zhang-Zhao]
  - Good(?) news: in case of CMOS power,  $\alpha \leq 3$  and thus may be considered a constant
- More good news: for the uniform version, we can find a solution with at most polylog(n) times the optimal cost in polynomial time







# Algorithm outline

- Partition traffic demands by bandwidth, in buckets [1, 2), [2, 4), [4, 8), ...
- Discretize cost function
- For each bucket, while there exist unrouted demands:
  - Solve LP relaxation and decompose fractional solution into well-cut-linked flows
  - Construct an expander graph as virtual network topology
  - Route (at least) some of the demands via edge-disjoint paths on the virtual topology
- Output the union of all partial routings

We need to ensure that each partial routing (i) serves at least a polylogarithmic fraction of the demands, and (ii) has cost at most polylog(n) times the optimum.

- Recall the analysis of the greedy set-cover algorithm...
  - However, a low ratio of cost / (#demands served) for every partial solution does not suffice in our case. We must bound the overall number of partial solutions as well.



# **Bucketing demands**

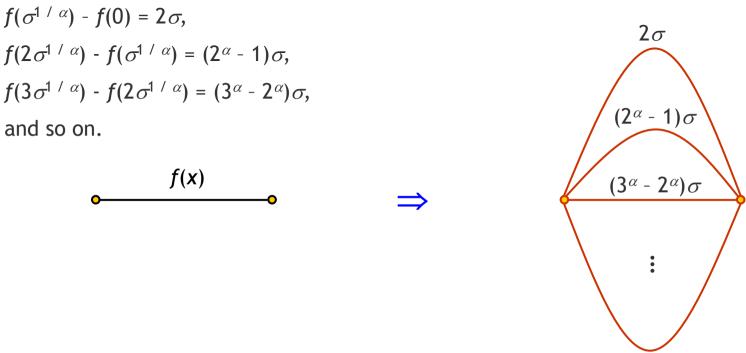
- Place demands with bandwidth [2<sup>j-1</sup>, 2<sup>j</sup>) in bucket j.
- Round up the bandwidth of all demands in bucket j to 2<sup>j</sup>.
  - Lose only a factor of 2 in the approximation.
- Henceforth, we deal with the demands in one bucket at a time.
  - All such demands have the same bandwidth (convenient).
  - W.l.o.g. we also assume that each demand has distinct endpoints (terminals) from other demands in the same bucket.
- For a bucket *j* such that  $2^j \ge \sigma^{1/\alpha}$ , replace the cost function with  $f^*(x) = 2x^{\alpha}$  at a loss of another factor 2 in the approximation.
  - Then, apply a CP-rounding algorithm from [Andrews-Fernandez-Zhang-Zhao] to route the demands in that bucket. ✓
- For a bucket *j* such that  $2^j < \sigma^{1/\alpha}$ , aggregate demands.
  - For simplicity, let's forget about aggregation; assume  $\sigma^{1/\alpha} = 1$  and unit demands...





#### **Discretizing the cost function**

• Replace each link by a collection of parallel edges, with a fixed **capacity** equal to  $\sigma^{1/\alpha}$ , and flat (step-function) costs:

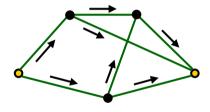


- Clearly, cheap edges will be used before expensive ones.
- Note: this transformation does not make the problem equivalent to Steiner forest, because of edge capacities.



# LP relaxation and well-cut-linked flows

- We formulate and solve an LP relaxation of the problem instance (including only the demands in the current bucket).
- In the (fractional) solution, each demand may be routed along more than one paths, each carrying only part of the demand's bandwidth.
  - These paths constitute a **flow** associated with the demand.
  - Not acceptable as a solution to our problem.
- Decompose into well-cut-linked terminals [Chekuri-Khanna-Shepherd]



- Create node-disjoint subgraphs of original graph.
  - Discard demands with terminals in different subgraphs.
  - At least a certain fraction of demands survives.
- Salient property: In order to cut one such subgraph in two parts, we would have to remove edges carrying a substantial total amount of flow (in the above fractional solution), proportional to the smaller total remaining demand in either part.



# **Constructing an expander topology**

- When is a graph G' = (V', E') an expander?
  - Regular
  - Expansion: for any  $S \subset V'$  with  $|S| \subset |V'| / 2$ , the number of edges in the cut (S, V' S) is at least c|S|, for a constant c > 0.
- Very similar the property of well-cut-linked terminals we saw earlier.
  - But how to use it for expander construction?
  - Suppose we are given a routine that for any balanced partition (A, B) of a node set V\* produces a perfect matching. Then, we can construct an expander by calling this routine O(log<sup>2</sup> | V\*|) times. [Khandekar-Rao-Vazirani]
- We build an expander on the terminals of each subgraph of the decomposition.
  - Here, perfect matchings consist of entire **paths** joining terminals, not just edges.
  - Well-cut-linkedness ensures the existence of such a path-matching.
  - Result: a virtual expander topology that uses each edge of the real topology at most a polylogarithmic number of times
    crucial for bounding

routing cost

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# Edge-disjoint routing in the virtual topology

- Given an expander and a set of node pairs (with each node belonging to at most one pair), we can route at least a polylogarithmic fraction of those pairs via edge-disjoint paths. [Rao-Zhou]
  - Expander graphs tend to have many short paths...
- Thus, in the real topology we can route at least a polylogarithmic fraction of the demands, while the load on every edge is at most polylogarithmically larger compared to the solution of the LP relaxation.
- We apply the same process on the remaining demands. No more than a polylogarithmic number of iterations required.

Putting it all together:

 Theorem. Uniform network design with (dis)economies of scale is polylog(n)approximable.





# **Concluding remarks**

- Applicability extends to more general cost functions (not necessarily polynomial) as long as they increase at least at a linear rate - but not too quickly, of course.
  - Asymptotically linear concave functions are also covered. In general, though, concave cost functions are better handled in the buy-at-bulk framework.

#### **Open questions**

- What is the (in)approximability of the non-uniform version?
- The intermediate capacitated problem may be viewed as a special case of Fixed Charge Network Flow, which has been well-studied from a heuristics perspective. Can our algorithm be adapted for the latter problem too?

# Thank you!

